

# Image and Video Person Identification in an Operational Environment

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- Project Start Date: **January 2016**
- Anticipated End Date: **December 2017**
- Project personnel:
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  - Yuhang Wu, PhD student

# Problem Statement

- **Identifying** individuals against both **known** and **unknown perpetrators** in the presence of unconstrained pose and arbitrary illumination conditions



# Biometric Identity: Applications

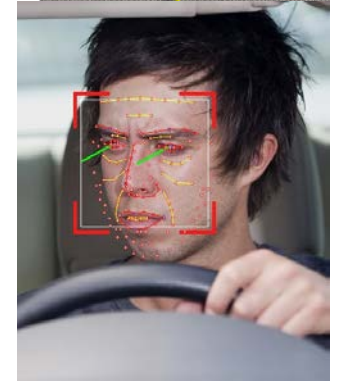
Air PoE



Game Cameras



Land PoE



# Beneficiary / End User Profile: Jobs

- DHS strategy officials: Analysts
- Enforcement Systems Division: Dispatchers

# Beneficiary / End User Profile: Desired Gains

- A method that will **accurately** identify individuals in **real-time** to enable the dispatchers to alert the agents dispatched in the field

# Beneficiary / End User Profile: Pain Points

- The methods currently available have **limitations** for matching images where a person's face is **partially visible** due to **pose** or **illumination**

# Products & Services

- The product is a **software prototype** for matching a facial image to a gallery of facial images with variety of poses and illuminations. The functionalities for the prototype software include:
  1. computing a biometric template (derived by the UH software) from an image
  2. ability to ingest a set of images to create a gallery
  3. matching biometric templates from a probe image to a gallery of templates

# Gains Created

- This product aims to enable the US BP dispatchers to accurately match images in existing databases by providing a beyond-state-of-the-art method for identification



# Pains Alleviated

- Enhancement of the overall situational awareness of the Border Patrol units
- USBP officer increased safety
- Effort and time savings
- Anticipation of future actions by modelling routes and habits of repeat offenders

# UHDB31 – Multi-View Facial Database

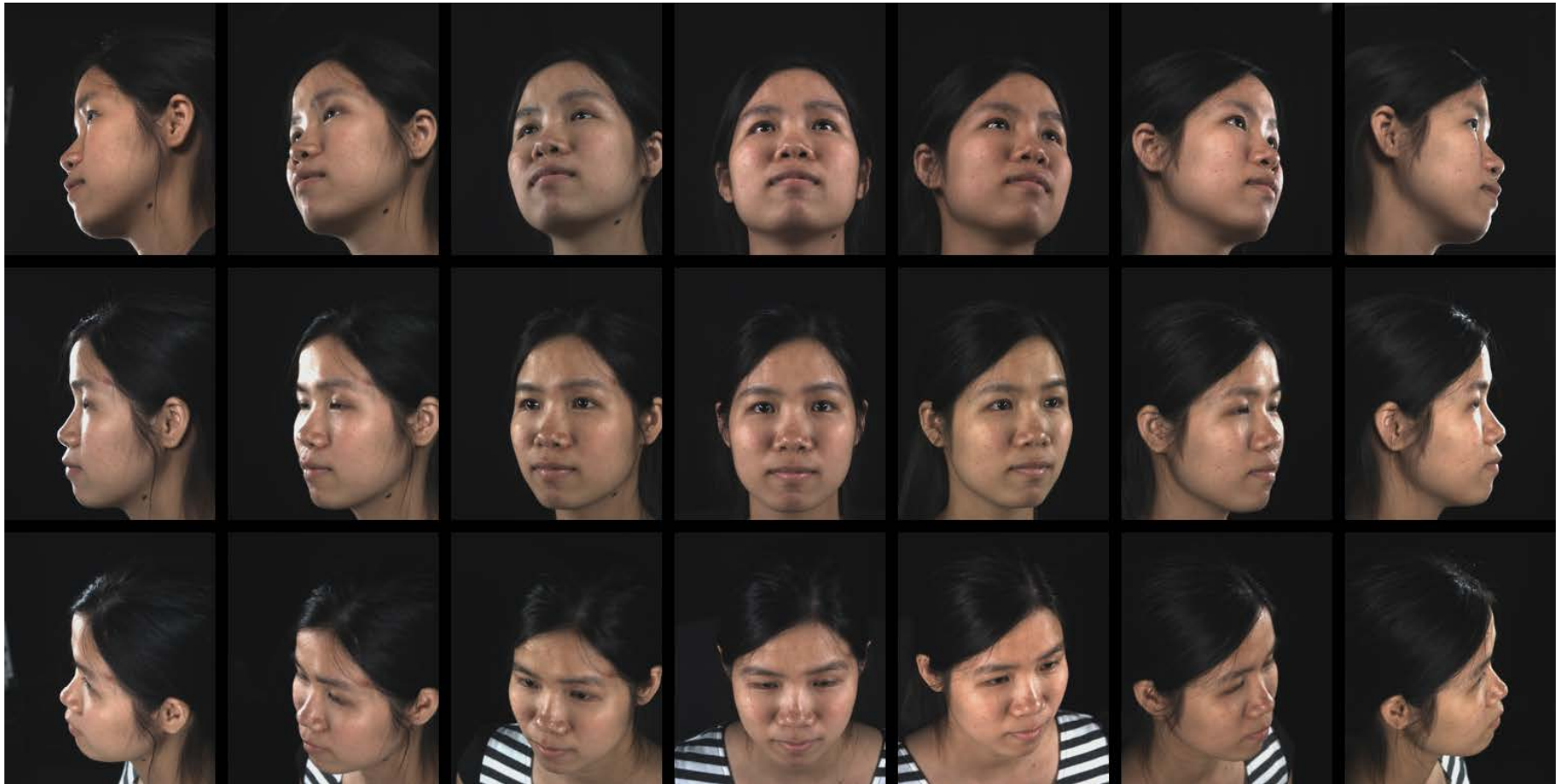


[1] Ha Le and Ioannis A. Kakadiaris, UHDB31: A Dataset for Better Understanding Face Recognition across Pose and Illumination Variation. In Proc. IEEE International Conference on Computer Vision Workshops. Venice, Italy. October 22-29 2017

# 21 Camera System



# 21 Pod Acquisition: 2D



# 21 Pod Acquisition: 2D



# UHDB31: Specifications

**Purpose:** Facilitates different experimental configurations, including 3D-3D, 3D-2D and 2D-2D, with pose and illumination variability

**Origin:** Acquired using a 21-pod system

**Data:** Both 2D images and 3D facial scans

**Number of subjects:** 77

**Resolutions:** Five different resolutions per image

**Pose variations:** 21 distinct facial poses

**Lighting conditions:** Three indoor lighting conditions

**Number of 3D facial scans:** 77 (one per subject) 3D facial scans






















**Number of 2D images:** 24,255 images

# UHDB31: Resolutions

Name	Image Size	Face ROI	IOD
UHDB31.R2048	2048x2448	1070x1070	536
UHDB31.R1024	1024x1224	535x535	268
UHDB31.R0512	512x612	267x267	134
UHDB31.R0256 *	256x306	134x134	67
UHDB31.R0128 *	128x153	64x67	34

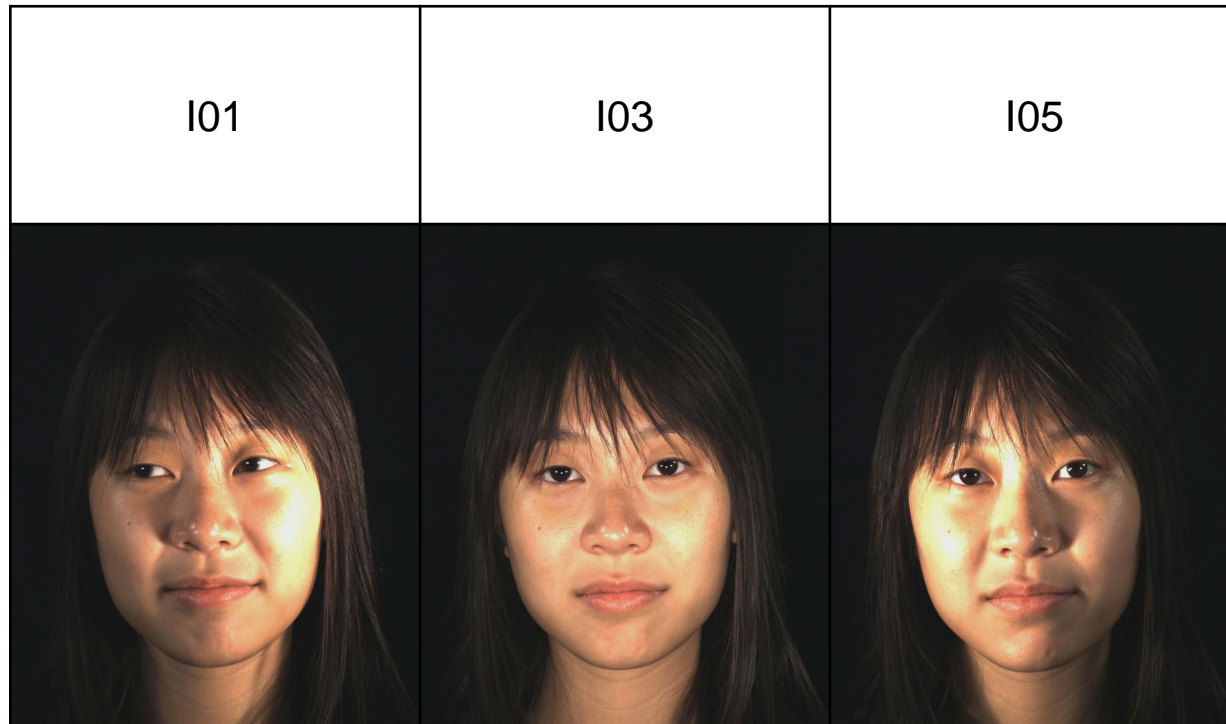
The last two cohorts marked with \* are used to evaluate the UH-URxD face recognition pipeline

# UHDB31: Pose Variations

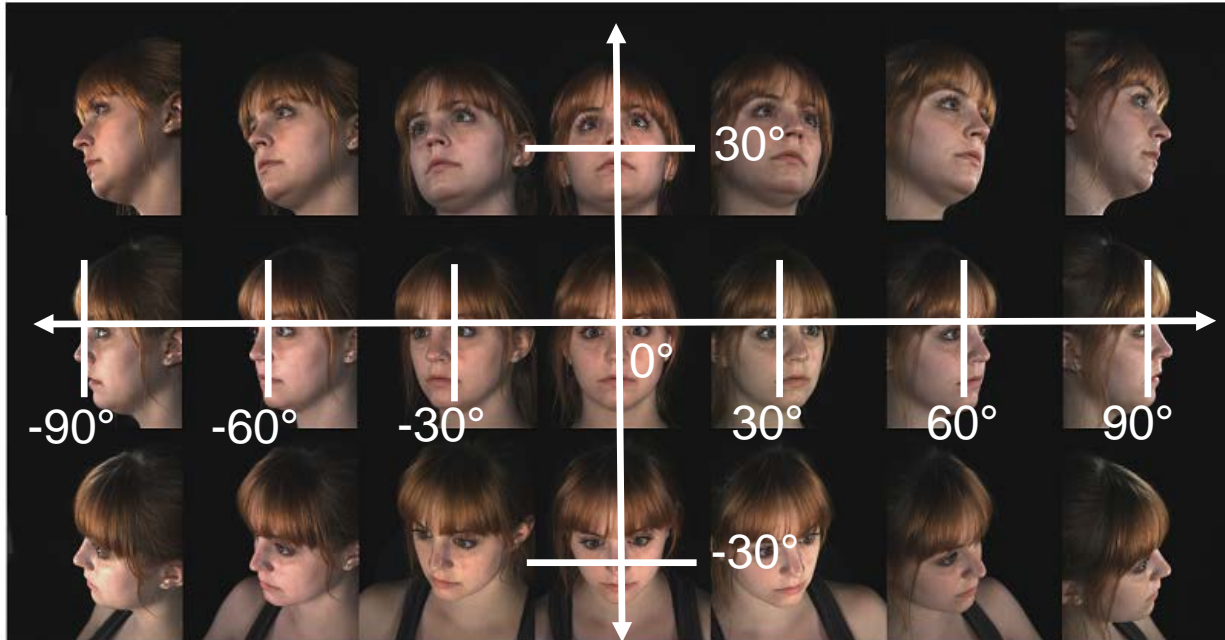
<b>Yaw Pitch</b>	<b>-90°</b>	<b>-60°</b>	<b>-30°</b>	<b>0°</b>	<b>30°</b>	<b>60°</b>	<b>90°</b>
<b>-30°</b>							
<b>0°</b>							
<b>30°</b>							



# UHDB31: Lighting Conditions



# UH-URxD performance on UHDB31.R0256.I03



This table illustrates the rank one rates of UH-URxD


# UH-URxD performance on UHDB31.R0256.I03



This table illustrates the rank one rates of UH-URxD

0.78						

# UH-URxD performance on UHDB31.R0256.I03



This table illustrates the rank one rates of UH-URxD

0.78	1					

# UH-URxD performance on UHDB31.R0256.I03



This table illustrates the rank one rates of UH-URxD

0.78	1	0.99	1	1	0.99	0.71
0.99	1	1		1	1	0.96
0.65	1	1	1	1	0.99	0.84

# UH-URxD performance on UHDB31.R0256.I03



This table illustrates the rank one rates of UH-URxD compared with VGG-Face [1] and COTS

<b>0.78</b> , 0.31, 0.03	<b>1</b> , 0.84, 0.40	<b>0.99</b> , <b>0.99</b> , 0.79	<b>1</b> , 0.97, 0.88	<b>1</b> , 0.99, 0.79	<b>0.99</b> , 0.87, 0.44	<b>0.71</b> , 0.43, 0.10
<b>0.99</b> , 0.62, 0.05	<b>1</b> , 0.95, 0.53	<b>1</b> , <b>1</b> , 0.94		<b>1</b> , <b>1</b> , 0.91	<b>1</b> , <b>1</b> , 0.68	<b>0.96</b> , 0.77, 0.10
<b>0.65</b> , 0.33, 0.01	<b>1</b> , 0.79, 0.13	<b>1</b> , 0.95, 0.68	<b>1</b> , 0.97, 0.91	<b>1</b> , 0.97, 0.81	<b>0.99</b> , 0.82, 0.17	<b>0.84</b> , 0.34, 0.08

[1] O. M. Parkhi, A. Vedaldi, A. Zisserman, Deep face recognition, in: Proc. British Machine Vision Conference, Swansea, UK, September 7-10, 2015, pp. 1-12

# UH-URxD performance on UHDB31.R0256.I01



This table illustrates the rank one rates of UH-URxD compared with VGG-Face [1] and COTS

<b>0.60</b> , 0.34, 0.01	<b>0.92</b> , 0.75, 0.09	<b>0.97</b> , 0.92, 0.60	<b>0.99</b> , 0.94, 0.74	<b>0.95</b> , 0.91, 0.43	<b>0.77</b> , 0.64, 0.07	<b>0.31</b> , 0.22, 0.03
<b>0.92</b> , 0.46, 0.07	<b>0.99</b> , 0.84, 0.22	<b>0.99</b> , 0.97, 0.82		<b>1</b> , <b>1</b> , 0.71	<b>1</b> , 0.86, 0.21	<b>0.57</b> , 0.31, 0.04
<b>0.52</b> , 0.20, 0.00	<b>0.95</b> , 0.51, 0.03	<b>0.99</b> , 0.83, 0.34	<b>1</b> , 0.92, 0.79	<b>1</b> , 0.88, 0.22	<b>0.83</b> , 0.55, 0.01	<b>0.18</b> , 0.09, 0.01

[1] O. M. Parkhi, A. Vedaldi, A. Zisserman, Deep face recognition, in: Proc. British Machine Vision Conference, Swansea, UK, September 7-10, 2015, pp. 1-12

# UH-URxD performance on UHDB31.R0256.I05



This table illustrates the rank one rates of UH-URxD compared with VGG-Face [1] and COTS

<b>0.21</b> , 0.13, 0.03	<b>0.71</b> , 0.51, 0.03	<b>0.97</b> , 0.87, 0.34	<b>1</b> , 0.91, 0.83	<b>1</b> , 0.95, 0.74	<b>0.99</b> , 0.77, 0.38	<b>0.66</b> , 0.48, 0.05
<b>0.58</b> , 0.26, 0.01	<b>0.97</b> , 0.78, 0.12	<b>0.99</b> , 0.96, 0.68		<b>1</b> , 0.99, 0.94	<b>1</b> , 0.91, 0.43	<b>0.91</b> , 0.64, 0.07
<b>0.18</b> , 0.17, 0.01	<b>0.82</b> , 0.48, 0.04	<b>0.94</b> , 0.77, 0.12	<b>0.99</b> , 0.91, 0.73	<b>1</b> , 0.88, 0.64	<b>0.99</b> , 0.69, 0.10	<b>0.56</b> , 0.29, 0.05

[1] O. M. Parkhi, A. Vedaldi, A. Zisserman, Deep face recognition, in: Proc. British Machine Vision Conference, Swansea, UK, September 7-10, 2015, pp. 1-12



# UH-URxD performance on UHDB31.R0128.I03



This table illustrates the rank one rates of UH-URxD compared with VGG-Face [1] and COTS [2]

<b>0.82</b> , 0.33, 0.05	<b>0.99</b> , 0.78, 0.40	<b>1</b> , 0.99, 0.74	<b>1</b> , 0.99, 0.88	<b>0.99</b> , <b>1</b> , 0.74	<b>0.99</b> , 0.87, 0.42	<b>0.75</b> , 0.40, 0.08
<b>0.96</b> , 0.62, 0.10	<b>1</b> , 0.96, 0.47	<b>1</b> , <b>1</b> , 0.91		<b>1</b> , <b>1</b> , 0.90	<b>1</b> , <b>1</b> , 0.64	<b>0.96</b> , 0.71, 0.10
<b>0.70</b> , 0.30, 0.03	<b>0.97</b> , 0.78, 0.10	<b>1</b> , 0.94, 0.66	<b>1</b> , 0.97, 0.91	<b>1</b> , 0.97, 0.82	<b>0.96</b> , 0.81, 0.18	<b>0.78</b> , 0.27, 0.07

[1] O. M. Parkhi, A. Vedaldi, A. Zisserman, Deep face recognition, in: Proc. British Machine Vision Conference, Swansea, UK, September 7-10, 2015, pp. 1-12

# UH-URxD performance on UHDB31.R0128.I01



This table illustrates the rank one rates of UH-URxD compared with VGG-Face [1] and COTS

<b>0.45</b> , 0.40, 0.04	<b>0.95</b> , 0.74, 0.10	<b>0.99</b> , 0.92, 0.60	<b>1</b> , 0.97, 0.71	<b>0.97</b> , 0.88, 0.39	<b>0.71</b> , 0.53, 0.08	<b>0.23</b> , 0.18, 0.00
<b>0.83</b> , 0.49, 0.07	<b>0.99</b> , 0.81, 0.20	<b>1</b> , 0.96, 0.77		<b>1</b> , 0.99, 0.73	<b>1</b> , 0.82, 0.18	<b>0.52</b> , 0.26, 0.03
<b>0.35</b> , 0.21, 0.01	<b>0.83</b> , 0.53, 0.04	<b>0.99</b> , 0.87, 0.30	<b>1</b> , 0.90, 0.74	<b>0.97</b> , 0.84, 0.16	<b>0.64</b> , 0.40, 0.03	<b>0.18</b> , 0.10, 0.07

[1] O. M. Parkhi, A. Vedaldi, A. Zisserman, Deep face recognition, in: Proc. British Machine Vision Conference, Swansea, UK,

# UH-URxD performance on UHDB31.R0128.I05



This table illustrates the rank one rates of UH-URxD compared with VGG-Face [1] and COTS

<b>0.16</b> , 0.13, 0.03	<b>0.69</b> , 0.49, 0.03	<b>0.99</b> , 0.82, 0.35	<b>1</b> , 0.91, 0.82	<b>0.97</b> , 0.90, 0.75	<b>0.96</b> , 0.79, 0.30	<b>0.66</b> , 0.47, 0.05
<b>0.48</b> , 0.23, 0.01	<b>0.92</b> , 0.73, 0.08	<b>0.99</b> , 0.96, 0.74		<b>1</b> , 0.74, 0.91	<b>1</b> , 0.94, 0.42	<b>0.88</b> , 0.53, 0.08
<b>0.12</b> , <b>0.13</b> , 0.05	<b>0.55</b> , 0.39, 0.05	<b>0.88</b> , 0.69, 0.17	<b>0.99</b> , 0.90, 0.71	<b>1</b> , 0.88, 0.58	<b>0.92</b> , 0.64, 0.09	<b>0.48</b> , 0.20, 0.01

[1] O. M. Parkhi, A. Vedaldi, A. Zisserman, Deep face recognition, in: Proc. British Machine Vision Conference, Swansea, UK, /

# Key accomplishments

		Face identification improvement rates (Percentage above SotA)			
Conditions		Rank-1		Rank-5	
pose	illumination	VGG-Face	COTS	VGG-Face	COTS
Large pose variation	Uniform illumination	26.6	<b>61.0</b>	14.4	<b>64.7</b>
	Non-uniform illumination	28.3	<b>60.9</b>	18.8	<b>63.4</b>

# Transition Pathways

- Testing of the prototype software on US BP data

# Transition Engagement

- US BP dispatchers utilization of the prototype software to match individuals
- Accuracy rates measured on the US BP data

# Transition Challenges (if applicable)

- Testing with real data

# Conclusions

- Face identification accuracy well beyond the projected performance improvement and well beyond the state of the art
- Gain: USBP enabled to assess potential threats by identifying persons of interest before they come in contact with the agents



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